

NOISE SOURCE IDENTIFICATION

Noise Source Identification (NSI) is an important method for optimising the noise emission from mechanical and electro-mechanical products.

The goal of NSI is to identify the most important sources on an object in terms of position, frequency content, and sound power. In some cases, this is supplemented with additional information that can assist in identifying the root cause and radiation mechanism involved.

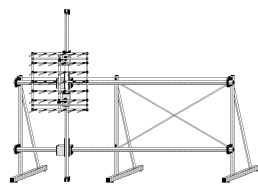
Direct measurement methods such as sound pressure mapping and sound intensity mapping are based on mapping the functions actually measured.

Indirect methods such as STSF and Beamforming rely on sound field propagation models to calculate sound field parameters in positions not directly measured. This not only provides more freedom in choosing where to measure but also provides a more complete understanding of the behaviour of the sound field.

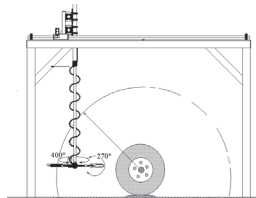
Since most methods involve measuring a large number of points, the measurement is most efficiently performed using an automated transducer positioning (robot) system and/or a microphone array.



Positioning System

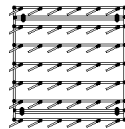


9665 Microphone Array Positioning System

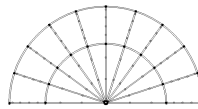


Automated Positioning System

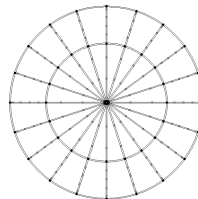
Microphone Arrays



Support Structure for Arrays
Ovoid Array for STSF

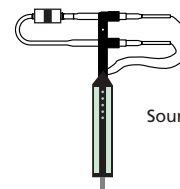


Semi-circular Beamforming Array

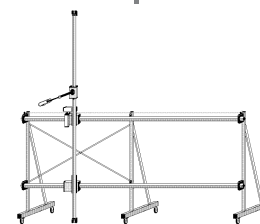


Circular Beamforming Array

Sound Intensity



Sound Intensity Probe



9654 Intensity Probe Positioning System
9665 Array Positioning System

020221

SOUND INTENSITY

- 3599 Sound Intensity Probe Kit
- 3541 Sound Intensity Calibrator
- 4297 Sound Intensity Calibrator
- 7759 Advanced Intensity Analysis

MICROPHONE ARRAYS

- 4935 Array Microphone
- 4944 Prepolarized Pressure-field Microphone
- WA 0728 6-channel Pistonphone Adaptor
- 4228 Pistonphone

WA 0806

Integral Connection Array (ICA)

WA 0807

Flexible Configuration array (FCA)

WA 0808

Vertical In-line Array (VIA)

WA 0890

Circular Beamformer Array

AO 0562

6-channel IDA Array Cable 10m

WA 0810

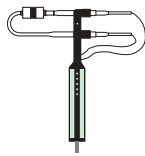
Stands for Array

TYPE 3560 C-S18

NSI System – Intensity

- 3560 C
- 7533
- 3032-A
- 7700-N2
- 7752
- 7761

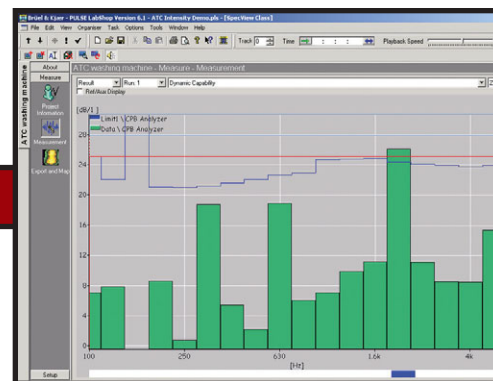
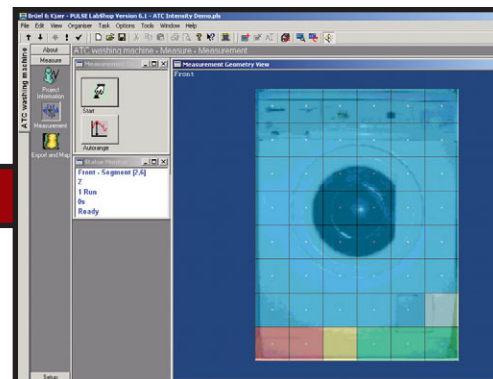
- Measurement and mapping of sound pressure, sound intensity and other directly measured sound field parameters
- Calculation of partial sound power for ranking of sub-sources
- Easy geometry-guided measuring process
- Intuitive documentation using source image overlay
- Expandable with:
Selective intensity mapping
Automated positioning system



The geometry-guided measurement process gives direct feedback on where to measure next and the quality of the measurements already performed

Data validation functions in ATC can be used to check measurements against limits, e.g., Dynamic Capability check of intensity measurements

* One year SW maintenance

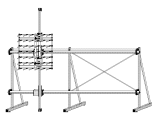


TYPE 3560 D-S19

**NSI STSF (12 In)
NSI STSF (30 In)**

- 3560 D
- 7536
- 2 x 3032-B
- 7770-N12
- 7752
- 7761
- 7780

- Mapping of sound pressure and sound intensity and other sound field parameters
- Transformation to parallel planes using acoustical holography
- Low to medium frequencies (0.1 to 5 kHz)
- Analysis of the full sound field or the part coherent to specific reference signals
- Calculation of partial sound power for ranking of sub-sources
- Easy geometry guided measuring process
- Intuitive documentation using source image overlay
- Expandable with:
Automated positioning system
Non-stationary STSF
Beamforming

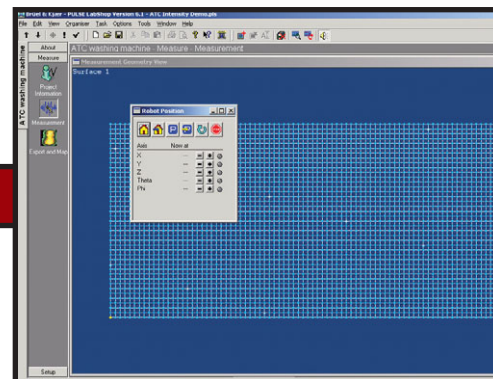
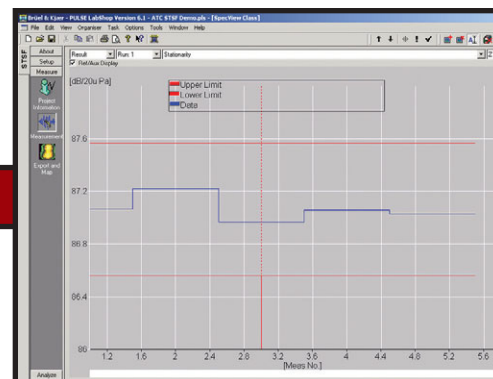


In STSF, data validation functions can be used to check the stationarity of the object measured by controlling the overall level of the reference signals

A robot may be used to automate scanned measurements. This not only saves time but also improves the positional accuracy and repeatability of the measurement points

- 3560 D
- 7536
- 4 x 3032-B
- 3232-A
- 7770-N16
- 7752
- 7761
- 7780

* One year SW maintenance



POSITIONING SYSTEM

- BZ 5370** Robot Option for Acoustic Test Consultant
- 9665** Array Positioning System
- 9654** Intensity Probe Positioning System
- WB 1477-002** STSF Motor Controller, 2 Axis

WB 1477-004

- STSF Motor Controller, 4 Axis
- WB 1477-006** STSF Motor Controller, 6 Axis
- WL 1090** STSF Motor Connection Cable

FRONT-END EXPANSION

- UH 1031** Fan Unit
- KQ 0155** Rack Cabinet
- UA 1365** Blank Module
- 3032** 6-channel General I/O Module

7536

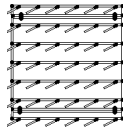
- 10/100 BaseTx LAN Controller Module
- 2826** Power Supply Module

TYPE 3560 E-S2

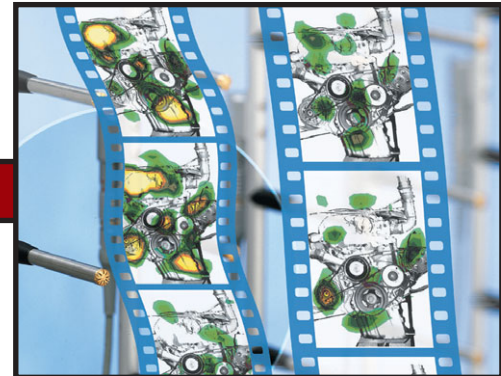
**NSI Non-stat STSF (36 In 3.2 kHz)
NSI Non-stat STSF (96 In 6.4 kHz)**

3560 E
7536
6 x 3032-B
7701
7712-D
7761
7770-N16

- Mapping of sound pressure and sound intensity and other sound field parameters – also as a function of time
- Averaging in Time, RPM, Angular or Cycle domain
- Order filtering
- Transformation to parallel planes using acoustical holography
- Low to medium frequencies (0.1 to 3 kHz)
- Calculation of partial sound power for ranking of sub-sources
- Easy one-shot measuring process
- Intuitive documentation including animation using source image overlay
- Expandable with:
STSF
Beamforming



Based on time domain acoustical holography, Non-stationary STSF supports noise mapping as a function of time, RPM or Shaft Angle. This provides new insight into the detailed behaviour of many products

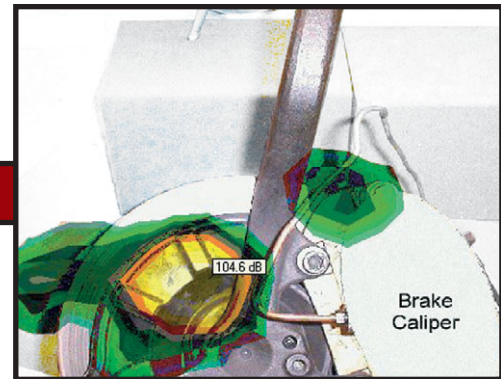


TYPE 3560 E-S3

2 x 3560-E
2 x 7536
15 x 3032-B
3032-A
7701
7707
7712-D
7761
7770-N16

* One year SW maintenance

Because of its high time resolution, Non-stationary STSF can also map transient and hard to reproduce events like brake squeals

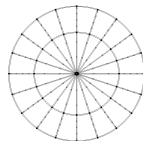


TYPE 3560 E-S4

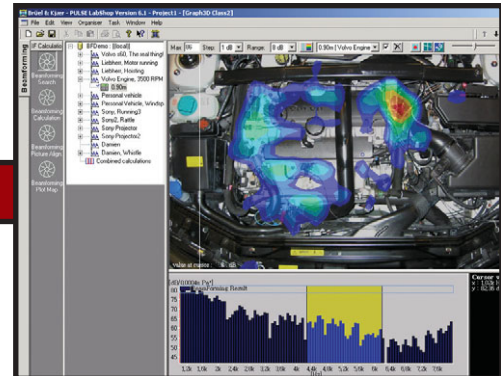
**NSI System Beamforming (42 In)
NSI System Beamforming (66 In)**

3560-E
7536
7 x 3032-B
7701
7752
7761
7768
7770-N16

- Mapping of relative sound pressure contribution
- Easy geometry-guided measuring process
- Intuitive documentation using source image overlay
- Well-suited for large objects
- Medium to high frequencies (0.5 to 20 kHz)
- Easy one-shot measuring process
- Intuitive documentation using source image overlay
- Expandable with:
STSF
Non-stationary STSF



Beamforming can quickly map objects also at high frequencies



TYPE 3560 E-S5

2 x 3560-E
2 x 7536
11 x 3032-B
7701
7707
7752
7761
7768
7770-N16

* One year SW maintenance

With synchronised map and spectral views, Noise Source Identification Type 7752 makes it easy to explore the source behaviour in terms of frequency and position

